

Nonlinear transduction of emotional facial expression

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Nonlinear transduction of emotional facial expression

2 Katie L.H. Gray¹, Tessa R. Flack², Miaomiao Yu³, Freya A. Lygo³ & Daniel H. Baker^{3,4} 3 1. School of Psychology and Clinical Language Sciences, University of Reading, Reading, RG6 4 6BZ, UK 5 2. School of Psychology, University of Lincoln, Brayford Pool, Lincoln, LN6 7TS, UK 6 3. Department of Psychology, University of York, Heslington, York, YO10 5DD, UK 7 4. York Biomedical Research Institute, University of York, Heslington, York, YO10 5DD, UK 8 Abstract 9 10 To create neural representations of external stimuli, the brain performs a number of 11 processing steps that transform its inputs. For fundamental attributes, such as stimulus 12 contrast, this involves one or more nonlinearities that are believed to optimise the neural code to represent features of the natural environment. Here we ask if the same is also true 13 14 of more complex stimulus dimensions, such as emotional facial expression. We report the 15 results of three experiments combining morphed facial stimuli with electrophysiological and 16 psychophysical methods to measure the function mapping emotional expression intensity to 17 internal response. The results converge on a nonlinearity that accelerates over weak 18 expressions, and then becomes compressive for stronger expressions, similar to the situation 19 for lower level stimulus properties. We further demonstrate that the nonlinearity is not 20 attributable to the morphing procedure used in stimulus generation. A preprint of this work 21 is available at: https://doi.org/10.31234/osf.io/svw8q

22 *Keywords*: emotional expressions; nonlinear transduction; SSVEP; psychophysics; morphing.

24 1. Introduction

25

Facial expressions are communicative tools; they signal an individual's emotional state and 26 27 motivation, and provide us with a wealth of information in social contexts (Adolphs, 2002; 28 Öhman, 2002). An expression can range from very subtle to very intense, and previous work 29 has used morphing software to parametrically manipulate emotional intensity within faces of 30 the same identity (Blair, Colledge, Murray, & Mitchell, 2001; Harris, Young, & Andrews, 2012; 31 Hess, Blairy, & Kleck, 1997). But how do changes in stimulus intensity map onto changes in 32 the brain's response to, and our perception of, another's face? Despite the importance of this 33 question for our understanding of perceived emotion, the precise mapping is currently 34 unclear.

35

36 Nonlinearities in the neural representation of low-level image features are very well 37 established. The brain responds to image contrast (defined as the luminance difference 38 between the brightest and darkest parts of an image, scaled by the mean luminance) 39 according to a saturating nonlinearity, that accelerates at intermediate contrasts, and 40 becomes shallow at higher contrasts. This pattern is consistent across measurements using psychophysical contrast discrimination, matching and scaling paradigms (Kingdom, 2016; 41 42 Legge & Foley, 1980), functional magnetic resonance imaging (fMRI; Boynton, Demb, Glover, 43 & Heeger, 1999), electroencephalography (EEG; Campbell & Kulikowski, 1972; Tsai, Wade, & 44 Norcia, 2012), single- and multi-unit recording (Albrecht & Hamilton, 1982; Busse, Wade, & 45 Carandini, 2009; Ohzawa, Sclar, & Freeman, 1982) and optical imaging using voltage sensitive dyes (Reynaud, Barthélemy, Masson, & Chavane, 2007). 46

48 Measuring neural responses to higher order stimulus properties (such as facial expression) is 49 possible using a fast periodic visual stimulation (FPVS) technique, which induces oscillations 50 in the EEG signal at specific frequencies. In this paradigm, 'oddball' target stimuli (e.g. faces 51 bearing an expression, or of a specific identity) are interleaved within a sequence of base 52 stimuli (e.g. neutral faces, or faces of a different identity) at a specific temporal frequency. If the target can be discriminated, responses are evident at harmonics of the oddball frequency 53 54 (Braddick, Wattam-Bell, & Atkinson, 1986; Liu-Shuang, Norcia, & Rossion, 2014). Most 55 previous studies have used high intensity expressions and made comparisons across different 56 configurations (e.g. upright and inverted; Coll, Murphy, Catmur, Bird, & Brewer, 2019; 57 Dzhelyova, Jacques, & Rossion, 2017). However, by parametrically varying the intensity of 58 emotional expression in the oddball stimulus, an 'emotion-response function' (analogous to 59 a contrast-response function) can be measured. This directly reveals the transfer function 60 between facial expression intensity and neural response. One recent study (Leleu et al., 2018) 61 has reported such an experiment, and shown evidence of nonlinear components in the 62 emotion-response function.

63

The perceptual consequences of neural nonlinearities can also be measured in a variety of 64 ways. For stimulus levels around detection threshold, the slope of the psychometric function 65 66 (the function relating stimulus intensity to accuracy in a two-alternative-forced-choice 67 detection task) depends on the underlying transducer nonlinearity in that region of stimulus 68 space (assuming no uncertainty about the task). A linear system will result in a shallow 69 psychometric function (Weibull β values around 1.3, see Meese & Summers, 2012; Pelli, 1985; 70 Tyler & Chen, 2000), whereas accelerating nonlinearities produce steeper slopes. There is 71 some evidence from recent work (Marneweck, Loftus, & Hammond, 2013) of slopes with β >

1.3 for discriminating four distinct emotional expressions from neutral, though deviation from
linearity was not formally assessed.

74

75 A complementary approach to characterize signal processing is to use a discrimination 76 paradigm, in which a participant's ability to detect differences in magnitude is measured at a 77 range of starting ('pedestal') levels (Nachmias & Sansbury, 1974). Relative to detection in the 78 absence of a pedestal, weak pedestal levels can reduce the target level required to reach 79 threshold performance (facilitation), whereas strong pedestal levels can increase thresholds 80 (masking). The combination of these effects creates a characteristic 'dipper' shaped function 81 (Legge & Foley, 1980) when threshold is plotted against pedestal level, that is determined by 82 the gradient (steepness) of the underlying nonlinearity. A linear system would not produce either the facilitation or masking effects, and thresholds should remain constant regardless 83 84 of pedestal level. Dipper functions have been reported for a range of sensory cues, including 85 motion (Gori, Mazzilli, Sandini, & Burr, 2011), blur (Watt & Morgan, 1983), depth (Georgeson, Yates, & Schofield, 2008), texture (Morgan, Chubb, & Solomon, 2008), duration (Burr, Silva, 86 87 Cicchini, Banks, & Morrone, 2009), loudness (Raab, Osman, & Rich, 1963), and amplitude modulation (Nelson & Carney, 2006), suggesting that the underlying nonlinearity is a common 88 89 property of perceptual systems.

90

91 One previous study has applied a similar paradigm to investigate the representation of facial 92 identity. Dakin and Omigie (2009) measured identity-strength discriminability of faces using 93 an odd-one-out paradigm. They morphed between an average identity face and a full identity 94 face in a number of steps. They then presented three faces: two identical faces (containing 95 the pedestal level of identity), and one face containing the pedestal identity with an additional

96 increment of identity. They repeated this at a number of different identity pedestal-levels, 97 measuring sensitivity at each level. When plotting threshold against pedestal identity, they 98 found evidence for shallow dipper-shaped functions, suggestive of a nonlinearity in the 99 representation of identity. However, these functions typically lacked the masking region 100 found for contrast (the dipper 'handle'). Work by Marenweck, Loftus and Hammond (2013) 101 reports discrimination for emotional expressions, but the pedestal level was not fixed within 102 a condition, making interpretation difficult. A primary aim of the present study is to 103 investigate whether emotional expression intensity is also subject to a process of nonlinear 104 transduction by measuring thresholds for expression discrimination at a range of pedestal 105 levels.

106

107 Here we report the results of three experiments. In the first we use an EEG paradigm to 108 measure neural responses to facial expressions in order to map out an emotion-response 109 function. In the second we measure the slope of the psychometric function for an expression 110 detection task. Finally, we assess the discriminability of emotional expressions from a range 111 of baseline (pedestal) levels. The results give a comprehensive picture of how expression 112 intensity information is processed to form an internal representation of others' emotional 113 states. We find evidence of a nonlinear transduction process similar to that reported for other 114 variables, which accelerates at low expression levels, and becomes shallower for more 115 intense expressions.

116

117 2. Methods

118

119 *2.1 Participants*

Twenty-four adult participants completed the EEG and detection experiments ($M_{age} = 23$; *SD* = 5.29; 5 males), and six participants completed the discrimination experiment (1 male). All had normal or corrected-to-normal visual acuity. All experiments were approved by the ethics committee of the Department of Psychology at the University of York, and written informed consent was obtained from all participants.

126

127 2.2 Apparatus and stimuli

128

129 All stimuli were derived from greyscale male and female faces taken from the NimStim face 130 set (Tottenham et al., 2009), depicting 6 basic emotional expressions (angry, fear, happy, sad, 131 surprise, and disgust; Ekman & Friesen, 1971). In the EEG and detection experiments, we used 132 16 female and 22 male identities, having a variety of racial backgrounds. For each identity, we 133 used a program (developed by Adams, Gray, Garner, & Graf, 2010) to morph between neutral 134 and an emotional expression in 6 steps, creating 7-levels of emotional intensity: 0, 6, 12, 24, 135 48, 96 and 144% (e.g. Calder et al., 2000; Calder, Young, Rowland, & Perrett, 1997). For the discrimination experiment, we also created an averaged identity for each gender (based on 136 137 19 female and 23 male exemplars), and then morphed between neutral and 150% expression 138 in 0.5% steps. External features (i.e. hair and ears) were removed from all faces using an 139 elliptical mask blurred by a cosine function. All stimuli were equated for mean luminance and 140 root-mean-square contrast.

141

In the EEG experiment, brain activity was recorded from 64 scalp locations laid out according
to the 10/20 system in a WaveGuard cap (ANT Neuro, Netherlands). We also monitored blinks

144 through bipolar electro-oculogram electrodes placed above and below the left eye. Signals 145 were amplified and digitised at 1kHz and recorded using the ANT Neuroscan software (ANT 146 Neuro, Netherlands). Stimuli were presented using a gamma corrected VIEWPixx display 147 (VPixx Technologies Inc., Quebec, Canada) with a resolution of 1920x1200 pixels, a mean 148 luminance of 50cd/m², and a refresh rate of 120Hz, controlled by an Apple Macintosh 149 computer. Trigger codes were sent from the VIEWPixx device to the EEG amplifier using a 25-150 pin parallel port to identify each condition and record stimulus onset times. The PsychToolbox 151 routines (Brainard, 1997) running in MATLAB were used to control the display hardware and 152 send triggers. The same display hardware was used in the detection experiment, but EEG 153 activity was not recorded. In the discrimination experiment, stimuli were centrally presented 154 on a gamma corrected 21-inch liyama VisionMaster Pro 510 monitor with a mean luminance of 32cd/m² and a resolution of 1152x768 pixels, driven at 75Hz by an Apple Macintosh 155 156 computer.

157

158 2.3 Procedures

159

EEG experiment: Sequences of faces were presented for trials of 60 seconds duration. Faces 160 161 subtended approximately 8x12 degrees of visual angle at the viewing distance of 57cm, and 162 were presented against a grey background with a central black fixation cross. The contrast of 163 the faces was modulated between 0 and 100% according to a 5Hz sine wave (see Figure 1a). 164 The identity of the face was changed at the minimum of each period (when the contrast was zero), resulting in a seamless stream of different identities. In this paradigm, each face 165 166 stimulus was presented for 200ms, but because contrast was 0 at the face onset and offset, 167 each face was visible for around 180ms. All stimuli had a neutral expression, except for an

168 'oddball' stimulus presented every fifth cycle (i.e. at 1Hz; see Figure 1a). This stimulus had a 169 randomly selected expression on each presentation, at a specific morph level that was 170 constant throughout the trial. Similar timings have been used previously with face stimuli (Liu-171 Shuang et al., 2014; Rossion, Prieto, Boremanse, Kuefner, & Van Belle, 2012) and appear to be a good compromise between potential floor and ceiling effects (i.e. too fast to allow 172 173 isolation of each individual response, or too slow to give large face-selective responses). 174 Participants were asked to fixate on a central cross for the duration of the trial and try to 175 minimise blinking; there was no behavioural task. Each block consisted of eight trials; one for 176 each morph level, plus an inversion condition using the 96% expression, but with all faces 177 rotated through 180 degrees. There was an inter-trial interval of 8 seconds. Each participant 178 completed four repetitions, taking around 40 minutes in total.

179

180 Detection experiment: We used a two-interval forced choice procedure that was designed to 181 closely mirror the temporal properties of the EEG experiment. Participants were presented 182 with two sequential streams of faces; a target stream containing a single emotional face 183 embedded within 8 neutral distractors, and a null stream containing only neutral faces. The target face always appeared on the fifth cycle (the midpoint of the target stream; see Figure 184 185 1b). The target and distractors were random identities, and the same identity was never 186 repeated on two adjacent cycles. The two streams were separated by 500ms. Participants 187 were asked to detect which stream contained the emotional target, and indicated their 188 responses using a mouse. Target intensity, target expression, and target interval were 189 randomised across trials. There were 480 trials (60 per emotional intensity condition, 190 including 60 trials for the inversion condition at the 24% morph level), separated into 5 blocks, 191 taking around 40 minutes to complete.

193 Discrimination experiment: We used a two-interval forced choice procedure; on each trial, a 194 face (subtending 10x16 degrees at the viewing distance of 57cm) was presented centrally for 195 100ms in each of two intervals, separated by 400ms. One face had its expression set at the 196 pedestal level (the null stimulus; pedestal levels were 0, 15, 30, 45, 60 and 75%), the other 197 face had its expression set at the pedestal level plus an increment (the target stimulus). 198 Participants indicated which interval contained the face with the strongest expression 199 intensity (i.e. the target) using a mouse. In additional conditions, pedestal and target stimuli 200 were applied to different halves of the face; the results of these conditions will be reported 201 in a subsequent publication. Stimuli were surrounded by a black square, and divided 202 horizontally by a black line. The purpose of the black line was to mask luminance 203 discontinuities caused by combining upper and lower face halves from different expression 204 intensities in some conditions, and is consistent with standard composite effect procedures 205 (Rossion, 2013). The gender of the face was chosen randomly on each trial (with equal 206 probability), but was the same across the null and target intervals. The expression was 207 constant across the null and target intervals, but was chosen at random on each trial in the 208 main experiment. On each trial, the level of the target increment was selected using a 209 staircase procedure (three-down, one-up, step size of 2.5%) that terminated after the lesser 210 of 70 trials or 12 reversals. Participants received auditory feedback on the accuracy of each 211 response. The main experiment took around 4.5 hours to complete for each participant, and 212 consisted of around 8000-9000 trials per participant (of which around ¼ are reported here). 213 We also ran a control experiment for a restricted set of pedestal levels, in which the 214 expression was fixed within a block.

215

218 *EEG experiment:* We took the Fourier transform of the EEG waveform (i.e. transformed the 219 responses from the time domain to the frequency domain) from each electrode for the 60 220 seconds during which stimuli were presented. There was a strong response from occipital 221 electrodes at the baseline frequency (5Hz) in all conditions, reflective of the general change 222 in contrast (and other image properties, such as identity) of the stimuli at this rate. Our 223 measure of interest was the amplitude at harmonics of the oddball frequency (1Hz), as this 224 measure is specific to emotional expression. To calculate the responses to the oddball stimuli, 225 we took the coherent average across repetitions and participants at 2, 3 and 4Hz, and then 226 averaged the amplitudes across these three frequencies to provide a single measure. We did 227 not include responses at 1Hz, as these were not distinguishable from the high noise levels in 228 this region of the spectrum (see Figure 1c), consistent with previous studies (Liu-Shuang et 229 al., 2014). We also excluded responses at and above the baseline frequency (>=5Hz), as these 230 are difficult to interpret given the strong contribution from the baseline flicker component.

231

232 Detection and discrimination experiments: Individual thresholds were estimated from each 233 participant's responses (as well as the pooled data in the detection experiment) by fitting a 234 cumulative Weibull function using the *quickypsy* package in *R* (Linares & López-Moliner, 235 2016). We defined threshold as the morph intensity required to reach 81.6% correct (i.e. the 236 balance point of the Weibull function), and the slope as the β parameter of the fit.

237

Data and code availability: Primary analyses were performed in *R*. Analysis scripts and raw
data are available at: http://dx.doi.org/10.17605/OSF.IO/8MS4Y

241 3. Results

242

243 3.1 The emotion-response function is nonlinear

244

245 In our first experiment, we measured the neural response to stimuli of different emotional intensities using a steady-state FPVS EEG paradigm, in a group of 24 adults. Streams of face 246 247 images with random identities were presented at 5Hz, with every fifth 'oddball' image bearing 248 a randomly chosen emotion, and the remainder being neutral (see Figure 1a). When the 249 oddball faces were also neutral (i.e. had a 0% expression morph level) there were clear 250 responses only at the carrier modulation frequency of 5Hz (see Figure 1b). When the oddball 251 faces carried a strong expression, responses were also evident at harmonics of the oddball 252 frequency (i.e. multiples of 1Hz, see Figure 1c), and were strongest over parieto-occipital 253 electrodes in the right hemisphere. These responses increased monotonically with morph 254 level at each of the first three harmonics (2, 3 and 4Hz), as shown by the lines in Figure 1d, 255 and their average (orange-filled circles in Figure 1d). Consistent with previous work 256 (Dzhelyova et al., 2017), inverting all images in the stream generated a much weaker 257 expression-specific response, as shown by the green symbol in Figure 1d (paired t-test; t=5.29, 258 *df*=23, *p*=0.000023, *d*=1.1, BF=1025).

259

To assess the linearity of these data, we replotted the average across the first three harmonics on log-log axes (see Figure 1e). The best fit regression line to these data had a slope of 0.73, and the upper bound of a bootstrapped 95% confidence interval on this slope estimate was

- also below 1 (lower CI = 0.54; upper CI = 0.91). This is evidence of a compressive nonlinearity,
- 264 equivalent to $y = x^{0.73}$, where x is morph level.

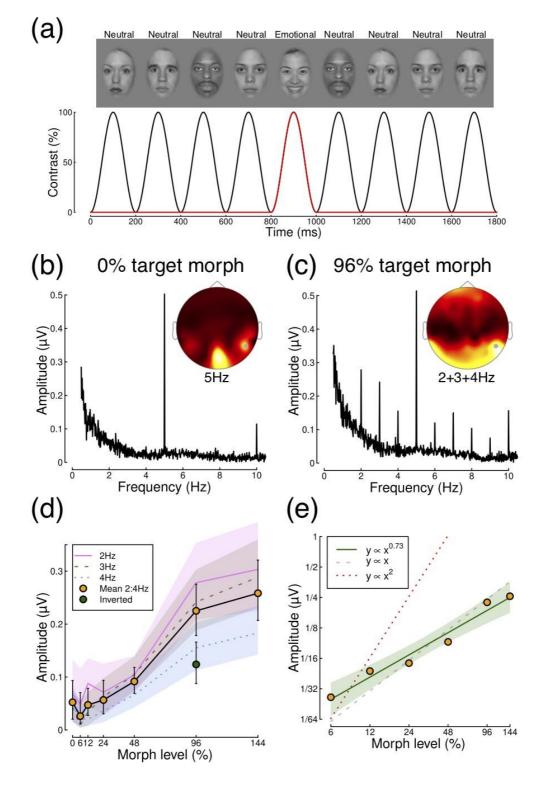


Figure 1: Neural SSVEP responses are lateralised and nonlinear. Panel (a) represents the stimuli presented during
a brief (1.8s) period of an extended (60s) trial. Stimulus contrast was sinusoidally modulated at 5Hz, with the

268 face image changed every 200ms at the trough of the modulation. An 'oddball' emotional face was presented 269 every 5 cycles, at a rate of 1Hz. Panel (b) shows the Fourier spectrum in the condition where the oddball stimuli 270 were also neutral, averaged across all participants (N=24). A strong response is evident at the modulation 271 frequency (5Hz), which is maximal at the occipital pole, with additional activity at more lateral sites. The 272 spectrum is derived from electrode P8, shown by the grey point. Panel (c) shows the Fourier spectrum for a 96% 273 target morph level. Here additional peaks in the spectrum are evident at integer frequencies. Panel (d) shows 274 emotion-response functions at individual frequencies (2, 3 and 4Hz) and their average (orange points). Shaded 275 regions and whiskers represent bootstrapped 95% confidence intervals across participants. Panel (e) shows the 276 average data replotted on log-log axes. Dashed and dotted lines show canonical predictions for a linear system 277 (dashed) and a squaring nonlinearity (dotted). The solid green line shows the best fit regression line in 278 logarithmic units, which has a slope of 0.73, with the green shaded region giving 95% confidence intervals of the 279 regression line.

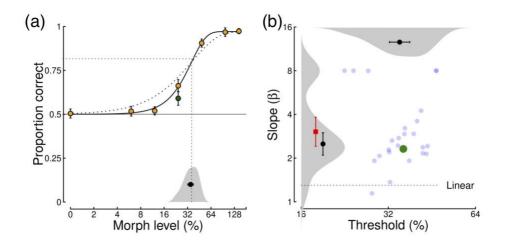
280

281 3.2 A nonlinear psychometric function for emotion detection

282

283 We next sought to measure the psychometric function for detection of emotional expressions 284 as a function of morph level. We based the stimulus sequence on that used in the SSVEP 285 experiment, and presented two sequences of 9 face images, each lasting 1.8 seconds (see Figure 1a). One sequence comprised only neutral faces, and the other contained an emotional 286 287 face as the fifth image. Participants indicated which sequence they believed contained the 288 emotional face. Performance increased monotonically as a function of morph level, from 289 chance performance at low morph levels (0-12%), reaching near ceiling performance for 290 morph levels of 96 and 144% (see Figure 2a). Again, there was an inversion effect (see green 291 point in Figure 2a), which reduced accuracy from 0.66 to 0.59 when the faces were presented 292 upside-down (paired t-test; *t*=3.19, *df*=23, *p*=0.004, *d*=0.65, BF=10.28).

293



294

295 Figure 2: Nonlinear psychometric functions for detection of emotional expression. Panel (a) shows the group 296 average psychometric function (N=24), along with the best fitting Weibull function (black solid curve). The grey 297 shaded region at the foot shows the distribution of individual thresholds, along with the mean (black point). The 298 black dotted curve is a Weibull function with the same threshold, but a slope of β = 1.3, showing the prediction 299 for a linear system. Panel (b) shows individually fitted thresholds and slopes (blue points), along with the fit to 300 the group average data (green). Grey shaded regions show distributions for each parameter, along with their 301 means across participants (black points). For slope values, the red square is the mean with the 4 outliers at β = 302 8 included, and the black point shows the mean with the outliers excluded. The dotted black line at β = 1.3 gives 303 the prediction for a linear system. Error bars in both panels show 95% confidence intervals.

305 We fitted a cumulative Weibull function to the group averaged psychometric function (see 306 solid curve in Figure 2a), and also to the functions for each individual participant (N=24), to 307 estimate the threshold and slope. The group average threshold at 81.6% correct occurred at 308 a morph level of 31.0%. This agreed well with the mean of the individual thresholds, which 309 was 30.9%. The psychometric slope for the group averaged data was β = 2.31, substantially 310 above the slope expected for a linear system of β = 1.3 (assuming no uncertainty). A psychometric function with a slope of β = 1.3 is shown by the dotted curve in Figure 2a, and 311 312 is a poor fit to the data. Because slope values can sometimes be underestimated for group 313 data if individual participants have different thresholds (see e.g. Wallis, Baker, Meese, &

Georgeson, 2013), we also assessed the slope values of individual fits (see Figure 2b). The geometric mean psychometric slope across the group was $\beta = 2.9$, which was also above the linear prediction of $\beta = 1.3$ (t=7.42, df=23, p<0.001, d=1.51, BF=101258). Four fits returned a slope at the upper bound of the permitted values ($\beta = 8$). When these participants were excluded, the geometric mean slope reduced to $\beta = 2.4$, which was still significantly steeper than $\beta = 1.3$ (t=8.88, df=19, p<0.001, d=1.98, BF=396167).

320

321 The slope value of $\beta \approx 2.4$ corresponds to an effective transduction exponent of 322 approximately 2.4/1.3 = 1.85. How can we reconcile this apparently accelerating nonlinearity 323 around detection threshold with the compressive nonlinearity implied by our EEG data? One 324 likely explanation is that the SSVEP paradigm was not sufficiently sensitive to detect responses in the sub-threshold range of morph levels (morph levels below 48% did not 325 326 generate responses that were reliably above the noise floor, see Figure 1d). On the other 327 hand, psychophysical performance had almost asymptoted by this morph level (see Figure 328 2a). The two results can therefore be considered complementary, as they reveal the 329 nonlinearities operating in different ranges of the stimulus continuum. This is also consistent 330 with other cues, such as contrast, which feature an accelerating nonlinearity around 331 threshold and a compressive regime at higher stimulus intensities (e.g. Legge & Foley, 1980; 332 Meese, Georgeson, & Baker, 2006). This combination of nonlinearities should result in a 333 'dipper' function for emotional expression intensity discrimination; our final experiment 334 investigates this prediction.

335

336 3.3 A 'dipper' function for emotion discrimination

338 We measured emotion discrimination functions in six participants using a two-interval forced 339 choice paradigm. To avoid the potentially complicating factors of temporal and identity 340 uncertainty that might stem from the stimulus presentation sequences used in the previous 341 experiments, we simplified the paradigm in two ways. First, only a single face was presented 342 on each interval of a trial. Second, this face was an averaged identity, created by morphing either male or female faces (see Figure 3a,b for examples). We measured discrimination at a 343 344 range of pedestal levels using a staircase method, and then fitted psychometric functions (see 345 Figure 2a) to estimate thresholds. A linear system should produce a completely flat function 346 for discrimination paradigms, where the pedestal level has no effect on threshold; any 347 modulation of thresholds is therefore evidence of nonlinear processing.

348

349 Thresholds at six pedestal morph levels are shown in Figure 3c. For a pedestal level of 0%, the 350 task is one of emotion detection. On average, participants required morph levels of around 351 29% to reliably detect (at 81.6% correct) the interval containing an emotional face (leftmost 352 point in Figure 3c). This compared closely with thresholds in the earlier experiment (mean of 353 31% morph level) using the method of constant stimuli with a different stimulus set and temporal sequence. For weak pedestal expressions (15% morph level) sensitivity to the target 354 355 increment improved (i.e. thresholds decreased) by around a factor of 1.6, showing evidence 356 of facilitation from the pedestal. At higher pedestal levels a masking effect occurred, whereby 357 increment thresholds were higher than without a pedestal. This pattern was evident for each 358 individual participant (red lines in Figure 3c). Overall, there was a substantial effect of 359 pedestal level on threshold (F(5,25)=23.49, p<0.001, $\eta^2=0.75$, BF=7758025) that was driven 360 by thresholds in the 0% pedestal condition being significantly higher than in the 15% pedestal 361 condition (*t*(5)=5.68, *p*=0.002, *d*=2.32, BF=20.72), and lower than in the 60% and 75% pedestal

362 conditions (t(5)=-3.33, p=0.021, d=1.36, BF=3.98; t(5)=-3.63, p=0.015, d=1.48, BF=5.06, 363 respectively). The slope of the rising limb of the dipper handle (estimated using linear 364 regression over the highest four pedestal contrasts) was 0.57 (95% CIs: 0.41, 0.73).

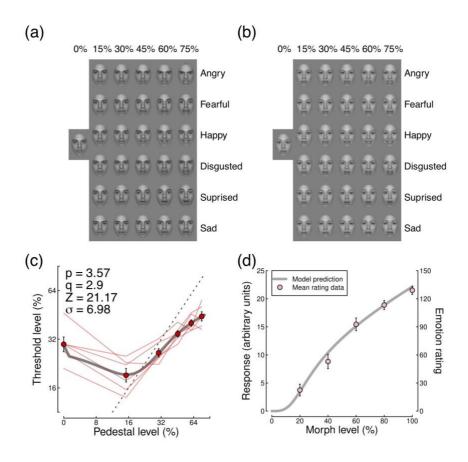




Figure 3: A dipper function for emotion discrimination. Panels (a,b) show example morphed facial stimuli for 6 expressions at the pedestal morph levels, for male (a) and female (b) averaged identities. Panel (c) shows the emotion discrimination function for individual participants (N=6, red lines) and their average (points; error bars show ±1SE). The grey curve shows the best model fit (see text for details), and the dashed oblique line has unit slope. Panel (d) shows the underlying emotion response function implied by the model fitted to the data in (c). Pink points replot the averaged data of Hess et al. (1997).

372

We fitted the average data with a standard nonlinear transducer function (Legge & Foley, 1980) with four free parameters. The response to a face of a given intensity level (*I*) is given by,

$$f(I) = \frac{I^p}{Z^q + I^q},\tag{1}$$

where *p*, *q*, and *Z* are free parameters. Thresholds are determined by calculating the increment level that satisfies $f(pedestal+increment) = f(pedestal) + \sigma$, where σ is a further free parameter that represents internal noise in the system. We determined best fitting parameters using a downhill simplex algorithm that minimised the least-squares error between data and model predictions. The best fitting curve is shown in Figure 3c, with parameters in the upper left corner. With four free parameters, the model provides an excellent description of the data, yielding an RMS error of 0.05dB.

385

386 In Figure 3d we plot the underlying transducer nonlinearity (the output of equation 1 for a 387 range of inputs) using the parameters derived from the fit in Figure 3c. The function has a 388 steep region around morph levels between 10% and 40% (i.e. around detection threshold), 389 but becomes shallower (compressive) at higher morph levels. This function represents the 390 way in which stimuli of different emotional intensities are mapped onto an internal response 391 scale, and shares several common features with the rating scale data of Hess et al. (1997), 392 most especially the shallowing at higher intensity levels. The points in Figure 3d replot the 393 data from Hess et al. (1997) averaged across expression (anger, disgust, happiness and 394 sadness) and face gender. It is clear that the data show extremely good correspondence with 395 the predictions of the model, with no additional free parameters required (though note that 396 the y-axes are scaled independently for the data points and the curve). In particular, the slope 397 of the function at high intensity levels accurately predicts that observed in the data.

399 3.4 Uncertainty reduction cannot explain the facilitation effect

400

401 An alternative explanation for facilitation effects that does not require a nonlinear transducer 402 is uncertainty reduction (Pelli, 1985). Under this account, at detection threshold an observer 403 is uncertain about which mechanisms to monitor and performs poorly. When the pedestal is 404 added, this helps the observer determine which mechanisms (or features of the stimulus) to 405 attend to, and performance improves (facilitation). Because the facial expressions shown in 406 our experiments were determined randomly on each trial, we wondered if the facilitation 407 effects could be explained by expression uncertainty. To test this, we conducted a control 408 experiment (on five participants) in which we blocked trials by emotion. Participants were 409 explicitly told at the beginning of a block of trials which emotion would be presented. All other 410 experimental parameters were the same as for the main dipper experiment.

411

412 Results for this control experiment are presented in Figure 4. For all expressions, a facilitation 413 effect was still observed at 15% pedestal level. There were variations in sensitivity across 414 expressions (circles; see also Marneweck et al., 2013); in particular thresholds were 415 somewhat higher for sad expressions (pink symbols) than they were for other expressions. 416 The average thresholds from the blocked conditions (black lines) were slightly lower than 417 those from the interleaved method used in the main experiment (red lines). A 2 (pedestal 418 level) x 2 (blocking condition) ANOVA showed a main effect of pedestal level (F(1,4)=47.79, 419 p=0.0023, $\eta_p^2=0.92$) but no effect of blocking condition (F(1,4)=3.63, p=0.13) or interaction 420 effect (*F*(1,4)=1.44, *p*=0.30). We can therefore conclude that uncertainty effects were minimal for our paradigm, and the dipper effect we report can be most straightforwardly explained 421 422 by a transducer nonlinearity.

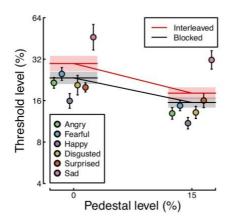


Figure 4: Facilitation effects occur for individual emotional expressions. Circles show thresholds for individual emotions for the blocked control conditions, and the black horizontal bars give their average. The red horizontal bars represent analogous conditions from the main experiment for the five participants who completed the control experiment. Error bars and shaded regions show ±1SE across participants (N=5).

428

429 4. Discussion

430

431 We have demonstrated a nonlinear mapping between the facial expression intensity in a 432 stimulus and the internal response magnitude evoked by that stimulus. Across three 433 experiments, we find that the nonlinearity is extremely similar to that reported for more basic 434 visual dimensions such as contrast. Responses are negligible at low intensities, rise steeply at 435 intermediate intensities around threshold, and exhibit a shallower, compressive portion at 436 high intensities (Figure 3d). The nonlinearity produces facilitation and masking effects in an 437 expression discrimination task, leading to a 'dipper' function similar to those reported for a 438 range of other sensory cues, and accurately predicts rating data from a previous study.

440 What is the purpose of this nonlinear transduction process for expression intensity? One 441 explanation for similar phenomena in contrast transduction (e.g. contrast gain control; 442 Carandini & Heeger, 2012; Heeger, 1992) is that they focus the greatest sensitivity in the 443 region of intensities most commonly experienced in the environment, or that is of most use 444 to the organism. In everyday social interactions, individuals rarely display extremes of 445 emotion with the intensities associated with our 100% morphs (middle image in Figure 1a). 446 Instead, most of the expressions we encounter in real life are weaker, and perhaps quite 447 fleeting. Yet it is crucially important that we are able to detect and discriminate changes in 448 these expressions to gauge the emotional states of our conspecifics. Therefore a mechanism 449 that is most sensitive to changes in weak emotions is likely to have been most useful during 450 human evolution. It is also likely that adaptation to emotional expressions (e.g. Adams et al., 2010; Butler, Oruc, Fox, & Barton, 2008; Fox & Barton, 2007; Juricevic & Webster, 2012; 451 452 Webster, Kaping, Mizokami, & Duhamel, 2004; Winston, Henson, Fine-Goulden, & Dolan, 453 2004) serves to maintain this sensitivity even when individuals display more extreme levels 454 of emotion on average.

455

The use of stimuli that are morphed along continua of expression or identity has become 456 457 increasingly common in face processing research. Yet some such studies implicitly assume 458 that linear steps in the morph space should correspond to linear differences in perception 459 (Blair et al., 2001; Orgeta & Phillips, 2008; Rotshtein, Henson, Treves, Driver, & Dolan, 2005). 460 Our data, along with those of others (Dakin & Omigie, 2009; Hess et al., 1997; Leleu et al., 461 2018), indicate that this assumption is incorrect. Our decision to use a neutral expression as 462 a baseline condition was arbitrary (see Young et al., 1997), and we anticipate that similar 463 results would be obtained when morphing between two emotional expressions (see Chen, Pan, & Chen, 2014 for preliminary evidence of this), or with other facial attributes associated
with character traits such as trustworthiness and dominance (Oosterhof & Todorov, 2008).
This suggests that multidimensional 'face space' accounts (e.g. Russell & Bullock, 1986;
Valentine, 1991) must become more complex than previously proposed, because of the need
to incorporate nonlinear processes that will distort the space (Tanaka, Giles, Kremen, &
Simon, 1998).

470

471 Category boundary effects for both emotional expression (Calder, Young, Perrett, Etcoff, & 472 Rowland, 1996; Etcoff & Magee, 1992) and facial identity (Beale & Keil, 1995) have been 473 widely reported, and can be considered a severe form of nonlinearity. Categorical processing 474 is typically defined by a rapid transition between categories (e.g. neutral and happy 475 expressions, or between two identities), and more similar perception or neural activity within 476 rather than between categories, even for comparable physical changes to the stimulus 477 (Rotshtein et al., 2005). We suspect our finding of a steep psychometric function for detection 478 (Figure 2), and a transducer that accelerates and then compresses (Figure 3d) might meet the 479 criteria often used for identifying categorical perception, and think it unlikely that our data 480 could discriminate between these two explanations. However, we note that category effects 481 are formally equivalent to high-threshold theory, which has been widely discredited for low-482 level cues in favour of a signal detection theory approach (Nachmias, 1981; Tyler & Chen, 483 2000). Characterising the underlying nonlinearity, as we have done here, offers greater 484 explanatory and predictive power (e.g. Figure 3d) than positing a binary category boundary.

485

Alternatively, it may be that different brain regions contain categorical and continuous
representations of emotional expression, with evidence that cortical regions in the temporal

lobe contain a continuous representation, whereas subcortical structures including the amygdala contain a categorical representation (Harris et al., 2012). Since subcortical structures are too deep for EEG to probe directly, our SSVEP signals most likely originate in cortical regions from which EEG activity can be detected, explaining the continuous response we report (see Figure 1e). On the other hand, cortical responses might also relay activity from subcortical regions, though presumably further processing would be applied in cortex that might change the nature of the response.

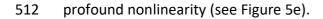
495

496 *4.1 Alternative metrics still support nonlinear processing*

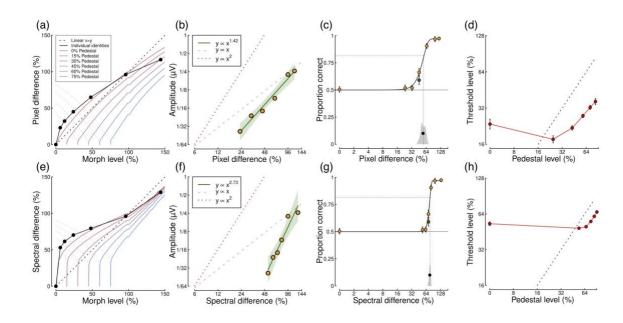
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498 In all our experiments we used a morphing technique to generate intermediate levels of 499 emotional expression. The morphing process produces a linearly increasing sequence of 500 expressions, but it manipulates the images geometrically in two dimensions, which could 501 introduce nonlinearities into the low level image features. In principle the apparently neural 502 nonlinearities we measure experimentally could be inherited from the stimuli if participant 503 responses were based on cues other than expression. We quantified this in two ways to 504 investigate whether image nonlinearities might be responsible for the apparently nonlinear 505 processing that we report. First, we measured the average absolute difference between pixels 506 in each successive morphed face image (the square root of the mean squared difference 507 produced a very similar result). This gives an aggregate measure of how local luminance 508 changes as a function of morph level, and shows evidence of a mild nonlinearity (see Figure 509 5a). Second, we measured the average absolute amplitude difference at each orientation and 510 spatial frequency in the Fourier transform of the images. This gives an indication of how the

511 global spectral content of the images changes as a function of morph level, and shows a more



513





515 Figure 5: Alternative metrics still support nonlinear processing. Panels (a,e) show how stimuli of different morph 516 levels differ in pixel luminance or Fourier amplitude. Black points show the estimates averaged across the 38 517 identities used in the first two experiments. Coloured curves show the estimates averaged across the male and 518 female examples used in the discrimination experiment, starting at different pedestal levels. In each case, the 519 values were divided by the difference at 100% (or 96%) morph level and expressed as a percentage, so that the 520 units were comparable to the morph level units used throughout the paper. The oblique dashed line shows the 521 expectation for a linear mapping between units. The remaining panels replot the data from Figures 1e, 2a and 522 3c using the alternative units, but with the same plotting conventions as described in the relevant figure 523 captions.

524

To understand how these alternative metrics might influence our conclusions, we re-ran our analyses replacing the (linear) morph levels with the pixel or spectral difference values (rescaled to be in analogous percentage units). Our rationale is that if the nonlinearity in the stimulus is responsible for (some of) the apparently nonlinear processing in the brain, using

529 these alternative units will result in more approximately linear processing. These results are 530 shown in Figure 5, and in Table 1 we report four indices of nonlinearity across the three experiments. Figures 5a,e show how the difference metrics change as a function of morph 531 532 level. If these were entirely linear all curves would run parallel to the oblique dashed unity line. Clearly there are some substantial deviations, however we note that the very steep 533 portion of the nonlinearity is at small morph levels (<15%) well below detection threshold 534 535 (see Figure 2a) where neural responses cannot be differentiated from noise (Figure 1d). This 536 means that the main influence of using these alternative units will be determined by the 537 shallower slope evident at higher morph levels.

538

Table 1: Summary of indices of nonlinearity for different candidate input units. The units summarise the main features of nonlinearity for each experiment, and comprise: the slope of the emotion response function (determined by linear regression on log-log values), the transducer exponent inferred by the slope of the psychometric function (Weibull β /1.3), the amount of facilitation given by the ratio of thresholds between 0% and 15% morph levels of the dipper function, and the slope of the dipper handle (over the four highest pedestal levels). These indices give evidence of nonlinear processing when they deviate from the linear predictions listed in the bottom row.

546

Input units	SSVEP slope	Weibull β /1.3	Facilitation	Handle
Morph level	0.73	1.78	1.55	0.57
Pixel difference	1.42	3.42	1.34	0.76
Spectral difference	2.73	9.95	1.09	0.90
Linear prediction	1	1	1	0

548 When using the pixel difference metric, the emotion response function (Figure 5b) and the 549 psychometric function (Figure 5c) are shifted to the right and become steeper. This is because over most of the range of stimulus levels the pixel differences increase with a slope of less 550 551 than 1 (compare points in Figure 5a with the oblique dashed line). This means that, relative 552 to using the morph level units, a smaller change in the stimulus is required to produce a unit 553 increase in response (or accuracy). The summary indices shown in Table 1 support this – the 554 slope of the emotion response function and the psychometric function both increase relative 555 to those derived using morph level units. The dipper functions also shift to the right and 556 become somewhat steeper, for similar reasons (see Figure 5d). However, the form of the 557 dipper is still apparent, with clear facilitation (a factor of 1.34), and masking in the 'handle' 558 region (with a slope of 0.76). All of these changes become more extreme for the spectral 559 difference metric (Figure 5f-h), yet in all cases there is still evidence of nonlinear processing 560 in the brain. Overall then, our main indices of nonlinearity are changed somewhat by the use 561 of image-based units, but we can still conclude that neural processing of emotion is nonlinear.

562

563 We think it relatively unlikely that these low-level image differences are actually used by participants for several reasons. In the psychophysical tasks, participants were explicitly 564 565 instructed to respond to the emotional content of the stimulus rather than image features 566 such as luminance, spatial frequency and orientation. Viewing the stimuli used in these experiments delivers a compelling subjective experience of changes in emotion, which 'pop 567 568 out' of the dynamic sequences used in the first two experiments (see Figure 1a). Because we used random identities in this temporal sequence, this will likely confound the low-level 569 570 changes that might be present within an identity. In addition, we observed strong inversion 571 effects (Eimer & Holmes, 2002; Yin, 1969) in the SSVEP and detection experiments (green

572 points in Figures 1d and 2a). For inverted stimuli, differences in low level image properties 573 remain constant, yet performance and neural responses are both significantly reduced 574 relative to upright stimuli. Finally, making reliable judgements about expression in everyday 575 life is unlikely to be possible using cues such as luminance, which will vary idiosyncratically 576 depending on the situation. It is conceivable that the visual system might use some of the 577 information from lower level features in combination with the expression information, yet 578 our analysis suggests that this would only increase the evidence for nonlinear neural 579 processing.

580

581 *3.3 Conclusions*

582

Across three experiments using different paradigms and stimuli, we find evidence that facial 583 584 expression intensity is processed in a nonlinear fashion. These findings are consistent with 585 the idea that relatively weak expressions are most typically experienced in everyday life, and 586 the brain might benefit from increasing sensitivity to subtle changes of expression within this 587 range. We predict that similar nonlinearities might apply along other dimensions of facespace, including facial identity, age, attractiveness, and facial features that communicate 588 589 character traits such as dominance and trustworthiness. Such nonlinearities would distort the 590 geometry of 'face space' in predictable ways that might be quantified in future studies using the methods developed here. 591

592

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600	6. References
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